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The chapter on model-reference adaptive control has been expanded substantially. The key results on stability theory are now derived from first principles. This makes it much easier to teach to students who lack a background in stability theory. A new section on adaptive control on nonlinear systems has also been added.

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5 Introduction History of Adaptive Control 6 ✕ 1950's Autopilots for high-performance aircrafts operating over a wide range of speeds and altitudes. ✕ 1960's Space state and stability theory. ✕ 1970's -1980's Proof for stability of adaptive

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Adaptive control is the control method used by a controller which must adapt to a controlled system with parameters which vary, or are initially uncertain. For example, as an aircraft flies, its mass will slowly decrease as a result of fuel consumption; a control law is needed that adapts itself to

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such changing conditions. Adaptive control is different from robust control in that it does not need a priori information about the bounds on these uncertain or time-varying parameters; robust control

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